



CAPSTONE

Advanced Process Control Solutions

CAPSTONE TECHNOLOGY CANADA



ABOUT THE COMPANY

Mission

Capstone Technology Canada (Inc 2002) is an Advanced Control technology and services company focusing on serving Canada's Oil & Gas industry

Experience

Over 100 years combined applications experience implementing and supporting APC solutions to multiple process industries

Expertise

Advanced process control engineering, model predictive control, multivariate modeling, real-time optimization

System Integrator

Integrator of partner technologies

APC Solution Experience

Extensive APC project experience with RMPC, DMC, Connoisseur, and Capstone Control technology

Locations

Employees located throughout Canada

CAPSTONE SERVICES AND SOLUTIONS

ADVANCED PROCESS CONTROL

Model Predictive Control

Soft Sensors

Real Time Optimization



ANALYTICS

Data Science, Analytics, and Data Mining

Dashboards and KPIs

Data Visualization



ADVANCED PLANNING AND SCHEDULING

Plant-wide Process Scheduling

Feedstock Planning and Scheduling

Debottlenecking and Optimization



APPLICATION DEVELOPMENT

Software Integration and Implementation

Software Development

Team Augmentation



CAPSTONE

OUR APC PHILOSOPHY

PROJECT CRITICAL SUCCESS FACTORS

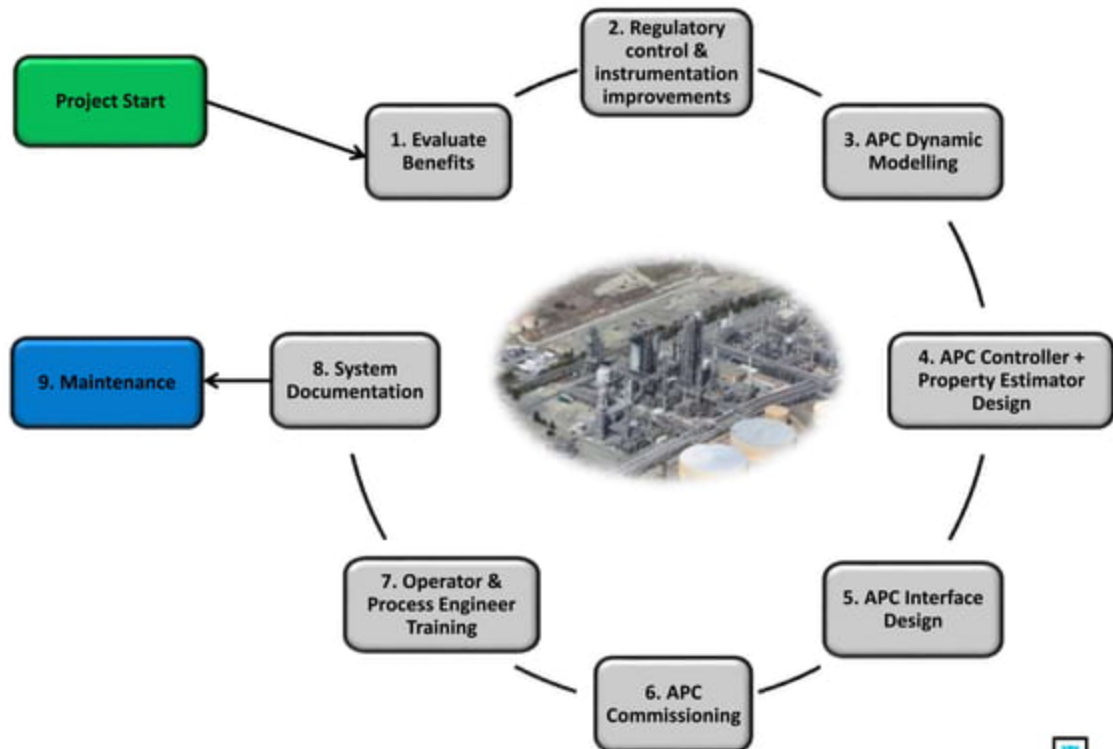


***** APC technology is proven and mature. Application success depends mainly on implementation.***

WHY CAPSTONE?

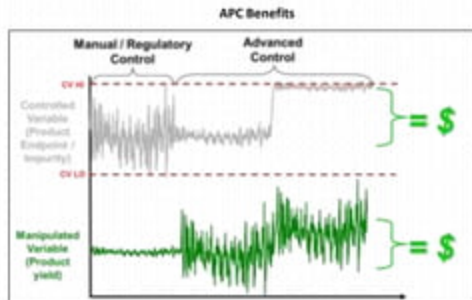
Success Factor	Why CAPSTONE?
Project Team	<ul style="list-style-type: none">• Extensive experience in APC-specific, Oil & Gas-specific applications• Experienced personnel assigned for entire project lifecycle, including site visits• Local project/support engineers ensures responsive support/training for Operations
Application Design	<ul style="list-style-type: none">• Depth of experience enables us to design the optimal solution for your specific application• Multi-platform integration expertise allows for cost effective project delivery• Experience integrating visualization tools with APC systems
Maintenance and Support	<ul style="list-style-type: none">• Long-term support of our applications at Canadian and International clients• Same-day response to service calls by a member of our team with extensive process, control, and systems engineering knowledge.
End User Engagement & APC Utilization	<ul style="list-style-type: none">• Track record of successful implementations resulting from high end user buy-in• Local presence facilitates effective training, support, and adoption of APC applications• APC and information systems support by our experienced team
Scope Prioritized Based on Business Case/Risk	<ul style="list-style-type: none">• Lower project risk through project risk management plan• Demonstrate business value to stakeholders by delivering benefits

APC PROJECT LIFECYCLE



1. BENEFITS ANALYSIS AND PRELIMINARY DESIGN

- Primary Benefits – variability reduction and optimizing operating point
- Identify control benefits by analyzing process areas
- Analyze historical and controlled step test data to estimate variability reduction
- Characterize process capability, mechanical and process constraints
- Identify instrumentation issues (tuning, loop pairing, etc), best operating practices, modes of operation, feed switches, etc.
- Combine the results of the analysis with economic data to estimate benefits

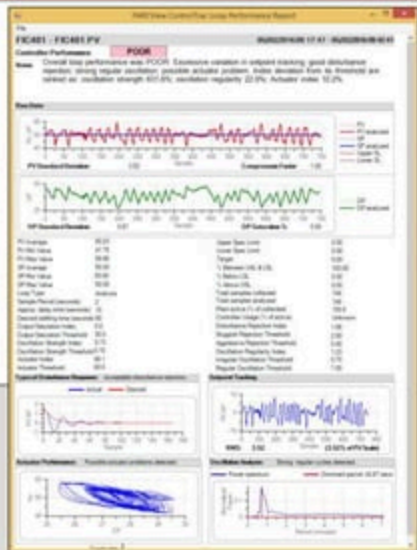


Deliverables, Milestones, and Outcomes

- Completed analysis of operating environment and initial optimization approach defined
- Dynamic control matrix
- Business case defined for each in-scope item
- Prioritized scope by business value & implementation risk
- Input to Phase 2 planning

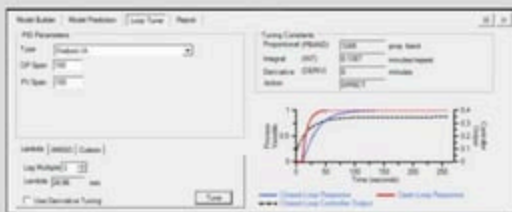
2. REGULATORY CONTROL + INSTRUMENTATION IMPROVEMENTS

- Re-tune main PID loops (as required) that will interface with APC
- Implement any recommended improvements to instrumentation



Deliverables, Milestones, and Outcomes

- Regulatory control systems are prepared for the APC project



3. DYNAMIC MODELING & STEP RESPONSE TESTING

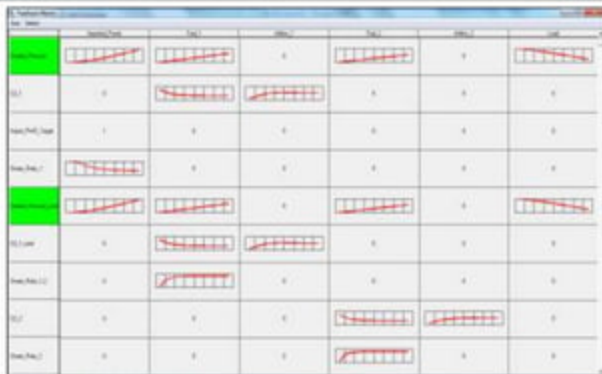
- Develop ***dynamic control models*** by fitting models to bump test data
- Determine ***test plan*** based on the operations analysis performed in Phase 1 and approved by Operations
- Include an experienced Board Operator as part of the project team. This individual often has a positive impact on ultimate 'end user' support.
- Operations is engaged to ensure that the process constraints are respected during the bump tests
- Several modeling packages available: Capstone's own or 3rd party

Deliverables, Milestones, and Outcomes

- Modelling approaches are defined
- Inputs to dynamic control models

4. APC CONTROLLER DESIGN

- Controller matrix is built from models identified during the previous phase
- Input/output tag mapping
- Initial tuning

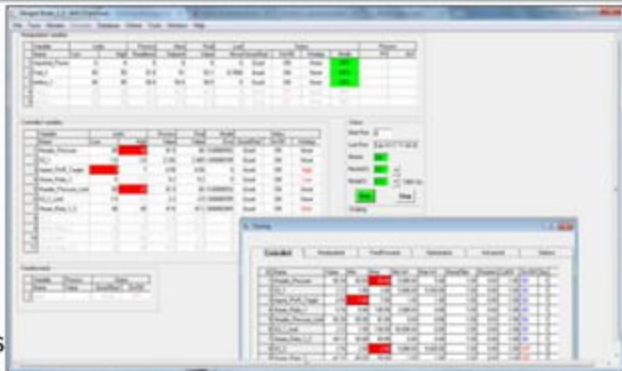


Deliverables, Milestones, and Outcomes

- Map for the control policy has been established

4. CONTROLLER DESIGN - CAPSTONE MODEL PREDICTIVE CONTROLLER FEATURES

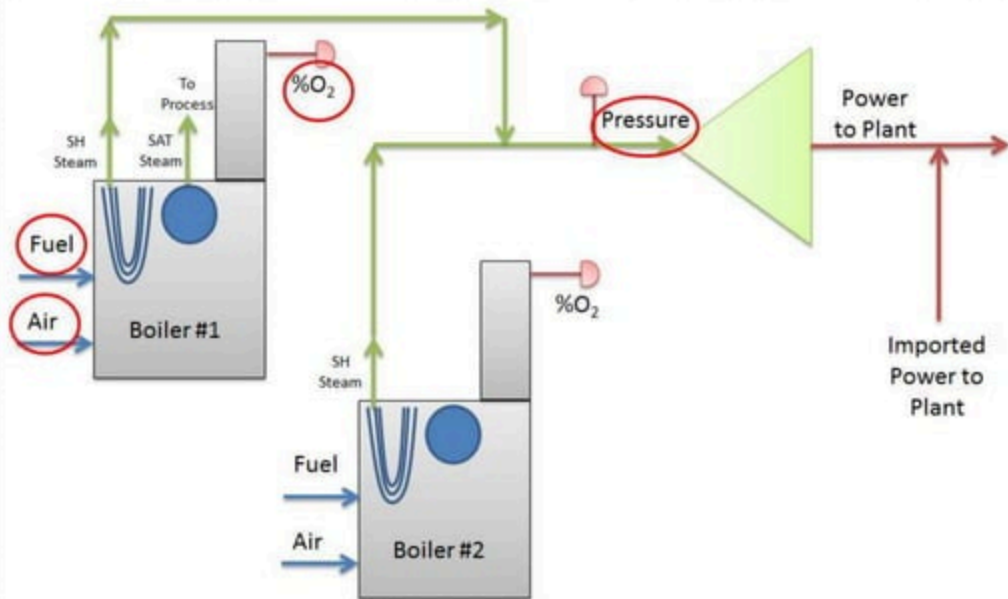
- Unlimited MV-CV pairings
- Predictive constraint control
- Optimization functionality: LP, QP
- Linear models may be used to map a non-linear response space through gain, lag and dead-time adaptation (allows for variable model parameters)
- Runs on Windows and has detailed server-side interface
- Reads/writes OPC
- Internal controller tags available for viewing in visualization tools through MPC data series



Deliverables, Milestones, and Outcomes

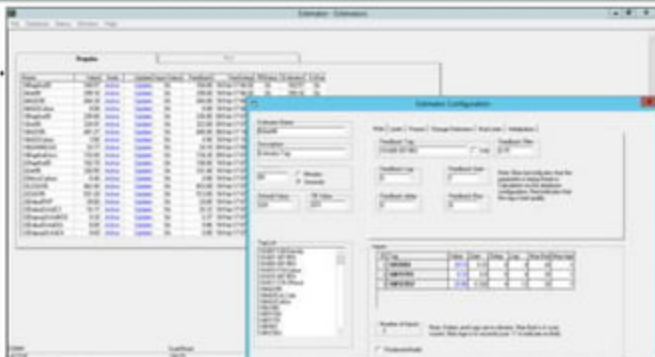
- Realize economic objectives for the application design
- Fine Tune the control policy to capture benefits

4. APC CONTROLLER DEMO



4. PROPERTY ESTIMATOR DESIGN - CAPSTONE PROPERTY ESTIMATOR FEATURES

- Provides a continuous estimate for properties measured infrequently (e.g. analyzer or lab measurements)
- Removes analyzer / lab delay
- Multi-input single output 1st order dynamic models; also supports multivariate gain models (PLS) combined with 1st order dynamics
- Internal estimator tags available for viewing in visualization tools



Deliverables, Milestones, and Outcomes

- Provides dead time compensated, continuous measurement(s) corrected by lab feedback, ready for control deployment.

5. APC INTERFACE DESIGN

- DCS Interface display - used by operators to engage/disengage APC, set targets/ranges, monitor instantaneous performance
- A similar display may be configured in visualization tools for users with no DCS access



Deliverables, Milestones, and Outcomes

- Primary HMI for the Control Room Operator

6. APC COMMISSIONING

- Work directly, on-site with Operations to ensure smooth transition to APC control
- Control Room Operators embedded in project team and support/participate in communicating commissioning activities to stakeholders
- Engage MVs and verify/modify initial tuning
- Tune applications to a satisfactory level of performance where they can remain permanently engaged



Deliverables, Milestones, and Outcomes

- Provide 1-on-1 operator training
- Document benefits obtained

7. OPERATOR & PROCESS ENGINEER TRAINING

- 1-on-1 operator training during previous phase
- Classroom training sessions for operator group
- Operator training focuses on:
 - process objectives, constraints
 - engagement/disengagement procedures
 - how the operator interacts with the interface
- Control Room Operators embedded in project team and support/participate in training sessions
- Process engineers are trained in detail on controller design and architecture

Deliverables, Milestones, and Outcomes

- Training curriculum
- Training courses

8. SYSTEM DOCUMENTATION

- Create detailed engineering documentation (needed for maintenance of the APC system)

Deliverables, Milestones, and Outcomes

- Detailed engineering documentation for the following:
 - Control strategy design
 - System architecture
 - DCS interface
 - Operating procedures

9. LONG-TERM MAINTENANCE

- Long-term performance benefits can be maintained in the absence of significant process changes with monitoring and maintenance
- Model predictive control performance may deteriorate over time due to process changes and if the initial models are no longer representative
- Typical changes may include: Unit revamps, equipment fouling, new or changed product specifications, instrumentation failures, etc

Deliverables, Milestones, and Outcomes

- Periodic monitoring program to ensure the performance and benefits are maintained
- Automated reports to monitor system performance
- Visualization package is often used to calculate, store and display KPIs, some examples:
 - App uptime
 - no. of MVs engaged or wound up
 - Economic benefits
 - Model mismatch size may be treated as SPC variables in visualization package
 - Alarms

VISUALIZATION



1. Tag Browser



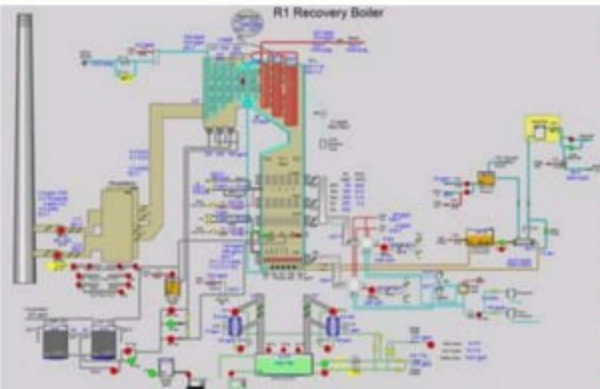
2. Tag Script Editor



Calc Engine



VISUALIZATION EXAMPLES



APPENDIX



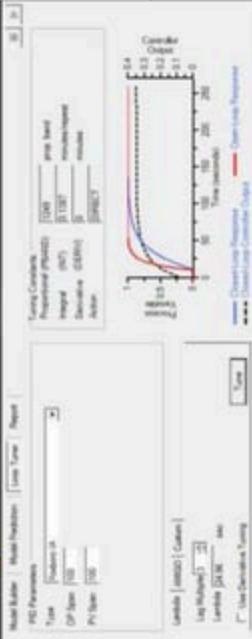
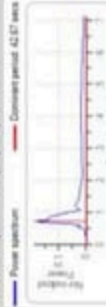
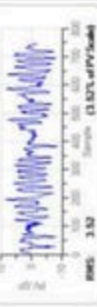
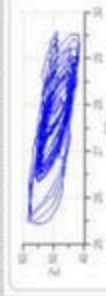
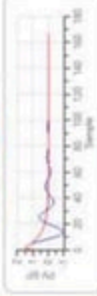
FMC401 - FIC401 PV

05/02/2016 17:47 - 05/02/2016 09:42:41

Controlled Performance: **POOR**

Product

Overall log performance was POOR. Excessive variation in septal tracking, good distance rejection, strong regular oscillation, possible actuator problem. Index deviation from its threshold are ranked as: oscillation strength 631.6%, oscillation regularity 22.9%, Actuator index 10.2%.



PROPERTY ESTIMATOR DESIGN - CAPSTONE PROPERTY ESTIMATOR FEATURES

Estimator - Estimators

File Database Status Window Help

Regular PLS

Name	Value	State	Update	Input Status	Feedback	Time/Stamp	FB Status	Estimator	Est/Stat
24kaphu95	168.57	Active	Update	Ok	168.00	10-Feb-17 06:00	Ok	168.57	Ok
24kwr95	299.16	Active	Update	Ok	299.00	10-Feb-17 06:00	Ok	299.16	Ok
24kGO95	444.24	Active	Update	Ok	446.00	10-Feb-17 06:00	Ok	444.24	Ok
24kGOColour	8.06	Active	Update	Ok	8.00	10-Feb-17 06:00	Ok	8.06	Ok
10kaphu95	235.86	Active	Update	Ok	236.00	09-Feb-17 07:05	Ok	235.86	Ok
10kwr95	324.91	Active	Update	Ok	323.00	09-Feb-17 07:05	Ok	324.91	Ok
10kGO95	481.27	Active	Update	Ok	485.00	08-Feb-17 11:19	Ok	481.27	Ok
10kGOColour	1.56	Active	Update	Ok	4.50	10-Feb-17 14:00	Ok	1.56	Ok
10GONRE SD	33.77	Active	Update	Ok	29.10	09-Feb-17 06:00	Ok	33.77	Ok
10kaphuVens	733.30	Active	Update	Ok	734.20	09-Feb-17 07:05	Ok	733.30	Ok
22kaphu95	182.79	Active	Update	Ok	196.00	10-Feb-17 07:05	Ok	182.79	Ok
22kwr95	326.55	Active	Update	Ok	331.00	10-Feb-17 07:05	Ok	326.55	Ok
22kMicroCarbon	0.48	Active	Update	Ok	0.88	10-Feb-17 07:05	Ok	0.48	Ok
22kGO95	462.40	Active	Update	Ok	453.00	10-Feb-17 07:05	Ok	462.40	Ok
22kGO95	531.26	Active	Update	Ok	513.00	10-Feb-17 07:05	Ok	531.26	Ok
22kphuRVP	29.80	Active	Update	Ok	29.80	10-Feb-17 07:05	Ok	29.80	Ok
22kphuOHdC3	16.17	Active	Update	Ok	20.32	10-Feb-17 07:05	Ok	16.17	Ok
22kphuOHdC4	0.24	Active	Update	Ok	0.37	10-Feb-17 07:05	Ok	0.24	Ok
22kphuOHdC6+	0.05	Active	Update	Ok	0.86	10-Feb-17 07:05	Ok	0.05	Ok
22kphuOHdC8	0.63	Active	Update	Ok	0.85	10-Feb-17 07:05	Ok	0.63	Ok

Estimator Configuration

Man | Links | Freeze | Change Detection | Bad Limits | Initialization

Estimator Name:

Description:

Frequency: ☐ Minutes ☒ Seconds

Default Value: FB Value:

Feedback Tag: ☐ Log

Feedback Filter:

Feedback Lag:

Feedback Gain:

Feedback delay:

Feedback Bias:

Note: Blue text indicates that the parameter is being Read or Calculated via the database configuration. Red indicates that the tag is bad quality.

Tag List

- 10-007-120-Censity
- 10-007-307-95%
- 10-009-307-95%
- 10-010-110-Colour
- 10-010-307-95%
- 10-011-115-SPred
- 10kGO95
- 10kGOCol_Calc
- 10kGOColour
- 10C1350
- 10F11750
- 10F11751
- 10F093
- 10FC553

Inputs

ID	Tag	Value	Gain	Delay	Lag	Max Bad	Max Age
1	10F1551	207.8	0.33	0	4	20	-1
2	10F11751	0.33	6.5	0	4	20	-1
3	10FC557	20.86	0.328	4	12	20	-1

Number of inputs: 3

Note: Delays and Lags are in minutes. Max Bad is in scan counts. Max Age is in seconds (use '1' to indicate no limit)

☐ Positional Model

COMM: ACTIVE

ScanFeed: ON 51

